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Abstract. Multistage processing of automated breast ultrasound lesions recognition is dependent on the performance of prior stages. To improve the current state of the art, we propose the use of end-to-end deep learning approaches using fully convolutional networks (FCNs), namely FCN-AlexNet, FCN-32s, FCN-16s, and FCN-8s for semantic segmentation of breast lesions. We use pretrained models based on ImageNet and transfer learning to overcome the issue of data deficiency. We evaluate our results on two datasets, which consist of a total of 113 malignant and 356 benign lesions. To assess the performance, we conduct fivefold cross validation using the following split: 70% for training data, 10% for validation data, and 20% testing data. The results showed that our proposed method performed better on benign lesions, with a top “mean Dice” score of 0.7626 with FCN-16s, when compared with the malignant lesions with a top mean Dice score of 0.5484 with FCN-8s. When considering the number of images with Dice score >0.5 , 89.6% of the benign lesions were successfully segmented and correctly recognised, whereas 60.6% of the malignant lesions were successfully segmented and correctly recognised. We conclude the paper by addressing the future challenges of the work. © 2018 Society of Photo-Optical Instrumentation Engineers (SPIE) [DOI: [10.1117/1.JMI.6.1.011007](https://doi.org/10.1117/1.JMI.6.1.011007)]

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1 Introduction

Breast cancer is the most common cancer in the UK,¹ where one in eight women will be diagnosed with breast cancer in their lifetime and one person is diagnosed every 10 min.¹ Over recent years, there has been significant research into using different image modalities² and technical methods have been developed^{3,4} to aid early detection and diagnosis of the disease. These efforts have led to further research challenges and a demand for robust computerized methods for cancer detection.

Two-view mammography is known as the gold standard for breast cancer diagnosis.² However, ultrasound is the standard complementary modality to increase the accuracy of diagnosis. Other alternatives include tomography and magnetic resonance; however, ultrasound is the most widely available option and widely used in clinical practice.⁵

Conventional computerized methods in breast ultrasound (BUS) cancer diagnosis comprise multiple stages, including pre-processing, detection of the region of interest (ROI), segmentation, and classification.^{6–8} These processes rely on handcrafted features including descriptions in the spatial domain (texture information, shape, and edge descriptors) and frequency domain. With the advancement of deep learning methods, we can detect and recognize objects without the need for handcrafted features. This paper presents the limitation of the state of the art and conducts a feasibility study on the use of a deep learning approach as an end-to-end solution for fully automated breast lesion recognition in ultrasound images.

Two-dimensional BUS lesion segmentation is a challenging task due to the speckle noise and being operator dependent. So far, image processing and conventional machine learning methods are deemed as preferable methods to segment the BUS lesions.⁹ These are dependent on the human designed features, such as texture descriptors^{10,11} and shape descriptors.⁷ With the help of these extracted features, image processing algorithms¹² are used to locate and segment the lesions. Some of the state-of-the-art segmentation solutions consist of multiple stages,^{13,14} preprocessing or denoising stage, initial lesion detection stage to identify an ROI,¹⁵ and segmentation.¹⁶ Recently, Huang et al.⁹ reviewed the BUS image segmentation solutions proposed in the past decade. In their study, they found that due to the ultrasound artifacts and to the lack of publicly available datasets for assessing the performance of the state-of-the-art algorithms, the BUS segmentation is still an open and challenging problem.

2 Related Work

This section summarises the state-of-the-art segmentation and classification approaches for BUS cancer analysis.

2.1 Breast Ultrasound Segmentation Approaches

Achieving an accurate segmentation in BUS images is considered to be a big challenge¹⁷ because of the appearance of sonographic tumors,^{18,19} the speckle noise, the low image contrast,

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and the local changes of image intensity.²⁰ Considering radiologist interaction within the segmentation process, it could have semiautomatic or fully automatic segmentation approaches.²¹

Semiautomated segmentation approaches require an interaction with the user such as setting seeds, specifying an initial boundary, or an ROI. For instance, in Ref. 22, a computerized segmentation method for breast lesions on ultrasound images was proposed. First, a contrast-limited adaptive histogram equalization was applied. Then, to enhance lesion boundary and remove speckle noise, an anisotropic diffusion filter was applied, guided by texture descriptors derived from a set of Gabor filters. Further, the derived filtered image was multiplied by a constraint Gaussian function, to eliminate the distant pixels that do not belong to the lesion. To create potential lesion boundaries, a marker-controlled watershed transformation algorithm was applied. Finally, the lesion contour was determined by evaluating the average radial derivative function.

To segment ultrasonic breast lesions, Gao et al.¹⁸ proposed a variant of a normalized cut (NCut) algorithm that was based on homogeneous patches (HP-NCut) in 2012. Further, HPs were spread within the same tissue region, which is more reliable to distinguish the different tissues for better segmentation. Finally in the segmentation stage, they used the NCut framework by considering the fuzzy distribution of textons within HPs as final image features. More recently, Prabhakar and Poonguzhali²³ developed an algorithm for an automatic segmentation and classification of breast lesions from ultrasound images. During the preprocessing step, speckle noise was removed using the Tetrolet filter and, subsequently, active contour models based on statistical features were applied to obtain an automatic segmentation. For the classification of breast lesions, a total of 40 features were extracted from the images, such as textural, morphological, and fractal features. Support vector machines (SVM) with a polynomial kernel for the combination of texture optimal features were used to classify the lesions from BUS images.

Fully automatic segmentation needs no user intervention at all. In Ref. 24, instead of using a term-by-term translation of diagnostic rules on intensity and texture, an algorithm to achieve a comprehensive decision upon these rules was proposed. This was achieved by incorporating image over-segmentation and lesion detection in a pairwise conditional random field (CRF) model. To propagate object-level cues to segments, multiple detection hypotheses were used. Further, a unified classifier was trained based on the concatenated features. This algorithm could avoid the limitations of bottom-up segmentation, and capable to handle very complicated cases. In the same year, an algorithm was proposed,¹⁹ making no assumptions about lesions, in which a hierarchical over-segmentation framework was used for collecting heterogeneous features. Considering multiscale property, the superpixels were classified with their confidences nested into the bottom layer. An efficient CRF model was used for making the ultimate segmentation. Compared with the other two different approaches, Hao et al.¹⁹ algorithm was superior in performance and was able to handle all kinds of tumors (benign and malignant).

In Ref. 25, two new concepts of neutrosophic subset and neutrosophic connectedness (neutro-connectedness) were defined to generalize the fuzzy subset and fuzzy connectedness. The newly proposed neutro-connectedness models the inherent uncertainty and indeterminacy of the spatial topological properties of the image. The proposed method was applied to a BUS

dataset with 131 cases, and its performance was evaluated using the similarity ratio, false positive ratio, and average Hausdorff error. In comparison with the fuzzy connectedness segmentation method, the proposed method was more accurate and robust in segmenting tumors in BUS images.

2.2 Breast Ultrasound Classification Approaches

The majority of state-of-the-art methods are multistage: first to detect a lesion, i.e., where a lesion is localized on the image.²⁶ The localization of a lesion can be done by manual annotation or using automated lesion detection approaches.^{6,15} Subsequently, the next step is to identify the lesion type using feature descriptors. Among different proposed approaches considering solid mass classification, there are two main feature descriptors,²⁷ i.e., echo texture^{11,28} and shape and margin features.²⁹ We present a couple of works on multistage machine learning methods. For a full review, please refer to Cheng et al.²⁶ Liu et al.³⁰ proposed a breast classification system for color Doppler flow imaging and B-mode ultrasound. To obtain features from the B-mode ultrasound, many feature extraction methods were used to provide both the texture and geometric features. The first stage was an extraction of color Doppler features, which was achieved by applying blood flow velocity analysis to Doppler signals to extract several spectrum features. In addition, the authors proposed a velocity coherent vector method. Furthermore, using a support vector machine classifier, selected features were used to classify breast lesions into benign or malignant classes. They achieved an area under the ROC curve of 0.9455 when validated on 105 cases with 50 benign and 55 malignant. In the same year, Yap et al.³¹ carried out a comprehensive analysis of the best feature descriptors and classifiers for BUS classification. They experimented with 19 features (texture, shape, and edge), 22 feature selection methods, and 10 classifiers. From their findings, the best combination was the feature set of four shape descriptors, one edge descriptor, and three texture descriptors using a radial basis function network, with an area under the ROC curve of 0.948. In 2016, Yap and Yap³² conducted a study to evaluate the performance of machine learning on human delineation and computer method. They found that there were no significant differences for benign lesions, but computer segmentation showed better accuracy for malignant lesion classification.

There is increasing interest in deep learning for medical imaging³³ and two research groups have been successful in using this in BUS. In 2016, Huynh et al.³⁴ proposed the use of a transfer learning approach for ultrasound breast images classification. The authors used 1125 cases and 2393 regions of interest for their experiment, where the ROIs were selected and labeled by the experts. To compare with the handcrafted features, CNN was used to extract the features. When classifying the CNN-extracted features with support vector machine on the recognition task of benign and malignant, they achieved an area under the ROC curve of 0.88. However, their solution was multistage and they did not share their dataset. In 2017, Yap et al.³⁵ demonstrated the use of deep learning for breast lesions detection, which outperformed the previous state-of-the-art image processing and conventional machine learning methods. They achieved an F-measure of 0.92 on breast lesions detection and made one of the dataset available for research purposes.

Recently, Yap et al.³⁶ demonstrated the practicality and feasibility of using a deep learning approach for automated semantic segmentation for BUS lesion recognition. However, they only performed onefold validation using one type of FCNs,

i.e., FCN-AlexNet. This paper extends Yap et al.³⁶ to fivefold cross validation on four types of FCNs, namely FCN-AlexNet, FCN-32s, FCN-16s, and FCN-8s. We are the first to implement semantic segmentation on BUS images.

3 Methodology

This section provides an overview of the BUS datasets, the preparation of the ground truth labeling, the proposed method, and the type of performance metrics used to validate our results.

3.1 Datasets

To date, data deficiency in medical imaging analysis is a common problem. To form a larger dataset, we combined two datasets, which were the only two datasets made available for researchers. We provide a summary for each dataset and the details can be found in Ref. 35.

In 2001, a professional didactic media file for breast imaging specialists³⁷ was made available. It was obtained with B&K Medical Panther 2002 and B&K Medical Hawk 2102 US systems with an 8- to 12-MHz linear array transducer. Dataset A consists of 306 images from different cases with a mean image size of 377×396 pixels. From these images, 306 contained one or more lesions. Within the lesion images, 60 images presented malignant masses [as in Fig. 1(a)] and 246 were benign lesions [as in Fig. 1(b)]. To obtain dataset A, the user needs to purchase the didactic media file from Prapavesis et al.³⁷ and Yap et al.³⁵ named it as dataset A in their description.

In 2012, the UDIAT Diagnostic Centre of the Parc Taulí Corporation, Sabadell (Spain) has collected dataset B with a Siemens ACUSON Sequoia C512 system 17L5 HD linear array transducer (8.5 MHz). The dataset consists of 163 images from different women with a mean image size of 760×570 pixels, where the images presented one or more lesions. Within the 163 lesion images, 53 were malignant lesions [as in Fig. 1(c)] and 110 with benign lesions [as in Fig. 1(d)]. Dataset B and the respective delineation of the breast lesions are available online for research purposes, please refer to Ref. 35, where they named it as dataset B in their description.

3.2 Ground Truth

As deep learning models for semantic segmentation are widely evaluated for the PASCAL-VOC 2012 training and validation dataset, these trained models are tested for various performance metrics on the PASCAL-VOC 2012 test set.^{38,39} In the PASCAL-VOC 2012 dataset, the RGB images are used as input images. The dimensions of both input images and label images should be the same size.⁴⁰ Although the images used in training are not required to be the same size for deep learning models in segmentation tasks, all the images are required to be of same size due to the use of fully connected layers in these models. In the labeled image, every pixel value for each class is an index ranging from 0 to 255. In the PASCAL-VOC 2012 dataset, there are a total of 21 classes used so far, hence, 21 indices are used for labeling the images. For BUS images, the format in the digital media is generally grayscale. Hence, to make this compatible with the pretrained models and networks that are trained for PASCAL-VOC 2012 dataset (RGB images), we converted the grayscale images to RGB images with the help of channel conversion. The ground truths in binary masks format are converted into the eight-bit paletted label images. Figure 1 shows the BUS images with the corresponding ground-truth labeling in PASCAL-VOC format, where index 1 (RED) indicates malignant lesion and index 2 (GREEN) indicates benign lesion.

3.3 Deep Learning Framework

The deep learning methods proved their superiority over image processing methods and traditional machine learning in the detection of abnormalities in medical imaging of various modalities.^{35,41} There are two main types of tasks associated with medical imaging, i.e., classification and semantic segmentation.^{42,43} However, a known limitation of the classification is its inability to locate the abnormalities in medical imaging. Hence, semantic segmentation of deep learning methods addresses this issue by classifying each pixel of the medical images rather than single prediction per image in the classification task. A popular group of deep learning methods

Fig. 1 Illustration of some images from the datasets and its ground-truth labeling in PASCAL-VOC format. (a) and (b) Images from dataset A, (c) and (d) images from dataset B; and index 1 (red) indicates malignant lesion and index 2 (green) indicates benign lesion.

for end-to-end semantic segmentation are fully convolutional networks (FCNs).⁴⁴

FCN-AlexNet is an FCN version of the original AlexNet classification model with a few adjustments in the network layers for the segmentation task.⁴⁴ This network was originally used for the classification of 1000 different objects of classes on the ImageNet dataset.⁴⁵ FCN-32s, FCN-16s, and FCN-8s are three models inspired by the VGG-16-based net, which is a 16-layer CNN architecture that participated in the ImageNet challenge 2014 and secured the first position in localization and second place in classification competition. All deep learning frameworks rely on feature extraction through the convolution layers, but classification networks throw away the spatial information in the fully connected layers. In contrast with the classification network that ignores spatial information using fully connected layers, FCN incorporates this information by replacing fully connected layers with convolution layers. Feature maps from those convolution layers are later used for classifying each pixel to get the semantic segmentation.

Transfer learning is a procedure where a CNN is trained to learn features for a broad domain after which layers of the CNN are fine-tuned to learn features of a more specific domain. Under this setting, the features and the network parameters are transferred from the broad domain to the specific one depending on several factors such as size of the new dataset and similarity to the original dataset. The use of the deep learning methods for semantic segmentation in medical imaging suffers from the problem of data deficiency, which can be overcome with the help of transfer learning approaches.^{41,42} In this work, the pre-trained models on the ImageNet dataset that contains >1.5 millions images of 1000 classes was used for transfer learning.⁴⁵ The weights trained on ImageNet dataset are transferred for semantic segmentation of BUS with minor adjustments in the convolutionized fully connected layers.⁴⁴ We initialized the weights of convolutional layers from these pretrained models rather than setting up the random weights for the limited medical datasets, such as BUS dataset. Otherwise, it is very hard to converge the models based on the limited medical datasets. Hence,

we fine-tuned these models using pretrained models and training on two classes, i.e., benign and malignant in the BUS dataset as shown in Fig. 2.

The combination of dataset A and dataset B forms a larger dataset with a total of 113 malignant lesions and 356 benign lesions. We used the combined dataset to form better training and transfer learning to overcome the problem of data deficiency. We used DIGITS V5, which acts as a wrapper for the deep learning Caffe framework on the GPU machine of the following configuration: (1) hardware: CPU—Intel i7-6700 @ 4.00 Ghz, GPU—NVIDIA TITAN × 12Gb, RAM – 32 Gb DDR5 and (2) deep learning framework: Caffe.⁴⁶

We assessed the performance of the model using fivefold cross validation using the following split: 70% for training data, 10% for validation data, and 20% testing data. We trained the model using stochastic gradient descent with a learning rate of 0.0001, 60 epochs with a dropout rate of 33%. The number of epochs was kept at 60 as in Ref. 47, where convergence has already happened when we performed the empirical experiments. Figure 3 shows the process of the end-to-end solution using semantic segmentation.

3.4 Evaluation Criteria

Even though the method is an end-to-end solution, we evaluated the results using standard performance metrics from the literature. To measure the accuracy of the segmentation results, the Dice similarity coefficient (henceforth, Dice)^{48,49} was used. We report our findings with Dice, sensitivity, precision, and Matthew correlation coefficient (MCC)⁵⁰ as our evaluation metrics.

4 Results and Discussion

Table 1 shows the performance of our proposed methods on benign and malignant lesions. Overall, all the methods performed better on benign lesions, with a top Dice score of 0.7626, compared with the malignant lesions with a top Dice score of 0.5484. The results showed that the performance of the proposed method was dependent on the size of the dataset.

Fig. 2 Transfer learning procedure of deep CNNs to obtain optimized weights initializations. Three fully connected layers of CNN were removed and replaced by three convolutional layers, making the pre-trained model fully convolutional.

Fig. 3 Overview of the semantic segmentation architecture.

Table 1 Summary of the performances for different lesion types for four semantic segmentation methods in mean. SD is a standard deviation.

Lesion type	Method	Sensitivity	Precision	Dice	MCC
		Mean $\pm$ SD	Mean $\pm$ SD	Mean $\pm$ SD	Mean $\pm$ SD
Benign	FCN-AlexNet	0.8000 $\pm$ 0.2404	0.7282 $\pm$ 0.2191	0.7199 $\pm$ 0.1964	0.7304 $\pm$ 0.1762
	FCN-32s	0.8271 $\pm$ 0.2250	0.7471 $\pm$ 0.1923	0.7473 $\pm$ 0.1896	0.7554 $\pm$ 0.1689
	FCN-16s	0.8374 $\pm$ 0.2392	0.7674 $\pm$ 0.1953	0.7626 $\pm$ 0.2095	0.7733 $\pm$ 0.1857
	FCN-8s	0.8092 $\pm$ 0.2683	0.7940 $\pm$ 0.1960	0.7564 $\pm$ 0.2373	0.7659 $\pm$ 0.2172
Malignant	FCN-AlexNet	0.4708 $\pm$ 0.3078	0.7599 $\pm$ 0.2364	0.4894 $\pm$ 0.2757	0.5080 $\pm$ 0.2488
	FCN-32s	0.4492 $\pm$ 0.2983	0.7737 $\pm$ 0.2925	0.3267 $\pm$ 0.2870	0.4001 $\pm$ 0.2577
	FCN-16s	0.3790 $\pm$ 0.2978	0.7481 $\pm$ 0.2718	0.4212 $\pm$ 0.2804	0.4616 $\pm$ 0.2527
	FCN-8s	0.5696 $\pm$ 0.3350	0.7044 $\pm$ 0.2528	0.5484 $\pm$ 0.2785	0.5842 $\pm$ 0.2358

In our datasets, we have more benign images (356) than malignant images (113). Overall, FCN-16s has the best performance in benign lesions recognition that achieved 0.8374 in sensitivity, 0.7626 in Dice score, and 0.7733 in MCC. FCN-8s has the best precision of 0.7940. For malignant lesions, FCN-8s is the best method with 0.5696 in sensitivity, 0.5484 in Dice, and 0.5842 in MCC.

According to Everingham et al.,⁵¹ the results with Dice score >0.5 are considered correct detection. Figure 4 compares the performances of the proposed methods when considering the number of images with Dice score >0.5 . Overall, benign lesions had higher Dice score, with top accuracy of 0.8960 for FCN-16s. This implies that 89.6% of the benign lesions were successfully segmented and correctly recognized. The results were comparable across four different methods. For malignant lesions, the top accuracy is 0.6060 with FCN-8s, where only 60.6% of the malignant lesions were successfully segmented and correctly recognized. The worst performance in malignant lesions recognition was FCN-32s, where only 33.3% of the lesions was successfully segmented and recognized. The poor performances were due to data deficiency in malignant class, which is a common issue for deep learning approaches.

To further illustrate the results, we visually compared the segmented regions for the proposed methods. Four examples of the successful and failed cases for our experiment are shown in Fig. 5. The first row is a benign lesion, where the lesion is

Fig. 4 The accuracy of the proposed methods when considering the number of images with Dice score >0.5 .

well defined with clear boundaries. All the methods achieved high Dice score. In Figure 5, the second row shows a malignant lesion with irregular boundaries and illdefined shape. We observed that all the methods had classified the lesion to the correct class. However, only FCN-16s managed to produce the closest segment when compared with the ground truth. The third row of Fig. 5 shows a benign lesion where all the methods failed to segment the lesion. Unlike cyst, the appearance of fibroadenoma is less hypoechoic, which is often difficult

Fig. 5 Visual comparison of the lesions segmentation and recognition with FCNs. (a) The ground truth delineation, (b) the proposed transfer learning FCN-AlexNet, (c) the proposed transfer learning FCN-32s, (d) the proposed transfer learning FCN-16s, and (e) the proposed transfer learning FCN-8s. The first and second rows showed the best-case scenarios, where the lesions were correctly segmented and classified. The third and fourth rows showed difficult cases where FCNs failed in those cases.

to segment from the surrounding normal tissues. The final row shows that even though the methods are able to segment the lesion, misclassification is an issue where FCN-AlexNet and FCN-32s have classified the hypoechoic region as benign. FCN-8s is able to classify the lesion correctly; however, it also detected some benign regions within the lesion. Overall, the lesions with small area, ambiguity in the boundary, and irregular shape are harder for semantic segmentation, due to the lack of data to represent these categories.

5 Conclusion

The common problems in conventional machine learning are: (1) It is based on hand-crafted features, (2) in some cases, it

requires human intervention where the radiologists have to select the ROI, and (3) it is multistage and there is dependency from one stage to the next. In this paper, the problem was solved using a deep learning approach where we have shown four types of FCNs in designing a robust end-to-end solution for BUS lesions recognition.

Conventional methods classified the lesion into a single type, but using semantic segmentation, we observed that it is not necessarily the case. As shown in Fig. 5 rows 3 and 4, one lesion may have both malignant tissue and benign tissue. This is an interesting finding for future research in understanding the tumour from both the computer vision and clinical perspectives.

This paper has provided new insight for future research by investigating four types of deep learning techniques. However, proposing an accurate end-to-end solution for BUS lesions recognition remains a challenge due to the lack of datasets to provide sufficient data representation. In the future, with the growth of big data and data sharing efforts, an end-to-end solution based on a deep learning approach may find wide applications in BUS computer-aided diagnosis.

Disclosures

No conflicts of interest, financial or otherwise, are declared by the authors.

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