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Semiparametric Accelerated Failure Time Model for Length-biased Data with Application to Dementia Study

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Abstract

A semiparametric accelerated failure time (AFT) model is proposed to evaluate the effects of risk factors on the unbiased failure times for the target population given the observed length-biased data. The analysis of length-biased data is complicated by informative right censoring due to the biased sampling mechanism, and consequently the techniques for conventional survival analysis are not applicable. We propose estimating equation methods for estimation and show the asymptotic properties of the proposed estimators. The small sample performance of the estimating methods are investigated and compared with that of existing methods under various underlying distributions and censoring mechanisms. We apply the proposed model and estimating methods to a prevalent cohort study, the Canadian Study of Health and Aging (CSHA), to evaluate the survival duration according to diagnosis of subtype of dementia.

Keywords

Accelerated failure time model; Dementia; Dependent censoring; Estimating equation; Length-biased sampling; Prevalent cohort

1. Introduction

Dementia is a common geriatric syndrome that affects more than 5 million Americans (Lee and Chodosh, 2009; Hebert et al., 2003). Among people older than 65 years in the United States, dementia is the fifth leading cause of death (Minino et al., 2007). Evaluation of survival duration from dementia onset has become an important public health issue, since life expectancy is increasing and consequently more older adults are being diagnosed with dementia. Although it is generally agreed that dementia shortens life expectancy, the estimated survival duration from the onset of dementia has a large variation, ranging from 3 to 9 years (Fitzpatrick et al., 2005; Helzner et al., 2008). Most of these estimates were based on prevalent cohort studies, in which subjects who were identified at recruitment to the studies were followed to record their time to death. Although prevalent sampling has been widely used in prospective cohort studies due to its convenience and economic considerations, estimation of survival duration could be inflated without adjustment for prevalent sampling bias. Wolfson et al. (2001) reported that the median survival estimate after adjustment for biased sampling is much shorter than the previously reported estimates that ignored the bias.

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Prevalent sampling has been widely used in prospective cohort studies, which involves the observance of left-truncated failure times with potential right censoring. Typically, subjects who have experienced the initiating event but have not experienced the failure event at the time of examination (or recruitment) are sampled into the cohort and followed prospectively for the failure event. The initiating event may be the onset or diagnosis of a disease, and the failure event may be death/recurrence of the disease. The time to the failure event may be right censored. It is clear that the subjects under observation comprise a subset of the original target population, and the subjects who did not survive to the examination times are left truncated. If the initial event (e.g. the onset of a disease) follows a stationary Poisson process, i.e., the truncation time follows a uniform distribution, these left-truncated data are called length-biased data. The assumption of a uniform truncation distribution can be examined by formal goodness-of-fit tests (Addona and Wolfson, 2006; Mandel and Betensky, 2007).

Length-biased data are often encountered in studies of epidemiologic cohorts, cancer prevention, and labor economy (Zelen and Feinleib, 1969; Lancaster, 1979; Vardi, 1989; Nowell and Stanley, 1991; De Una-Alvarez et al., 2003; Zelen, 2004; Greenberg et al., 2005; Song et al., 2006), in which the probability of an individual being selected from the target population is proportional to the duration from the first event to the failure event. Although the issues of length bias and the need to correct for bias in estimation and inference in various applications have been well recognized for decades in the epidemiology and statistics literature, considerable methodological gaps remain. Previous work has largely focused on one-sample estimates for the length-biased failure time distribution either conditional on the observed truncation times (Turnbull, 1976; Lagakos et al., 1988; Wang, 1991; Kalbfleisch and Lawless, 1991; Wang et al., 1993; Luo and Tsai, 2009), or with an unconditional approach (Vardi, 1982, 1989; Asgharian et al., 2002; Asgharian and Wolfson, 2005). There is little work considering regression analysis for modeling the association between risk factors and population failure times. Recently, under the proportional hazards model, Tsai (2009) extended the pseudo-partial likelihood approach of Wang (1996) and Qin and Shen (2010) proposed inverse weighted estimating equation approaches for right-censored length-biased data.

The accelerated failure time (AFT) model is an important alternative to Cox's proportional hazards model and has appealed to investigators because of its straightforward interpretation. Large sample properties and methods of inference have been extensively investigated over the last twenty years for traditional right-censored survival data (Prentice, 1978; Buckley and James, 1979; Miller and Halpern, 1982; Ritov, 1990; Tsiatis, 1990; Lai and Ying, 1991a; Ying, 1993; Lin and Ying, 1995; Jin et al., 2003). However, the length-biased sampling and the resultant violation of the assumption for independent censoring complicate the use of the AFT model on right-censored length-biased data. Recently, Chen (2010) and Mandel and Ritov (2010) utilized the invariant property of the covariate effects in the AFT model to propose estimating methods for length-biased data not subject to right censoring. When length-biased failure times are subject to right censoring, the aforementioned methods cannot be easily extended to accommodate the induced dependent censoring. Shen et al. (2009) proposed an estimating equation approach under the transformation model as well as the AFT model. The advantage of the estimating equation approach is its ease in calculation because of the closed form of the solution for the estimating equations. However, the equations are based on the first moment property of the observed failure times, which may not be efficient. In a subsequent paper, Ning et al. (2011) generalized a Buckley-James type of estimator in traditional survival analysis of length-biased data. The proposed estimators under the AFT model have pros and cons under different scenarios. Hence, it is desirable to develop more efficient estimation methods

under the AFT model given right-censored length-biased data and compare their performance for various censoring distributions and underlying distributions.

Our goal in this paper is to use the semiparametric AFT model to infer the relationship between the unbiased survival time and the diagnosis of a subtype of dementia using data from the Canadian Study of Health and Aging (CSHA). The CSHA is a large national epidemiology study of dementia and other health problems of people aged 65 years and over in Canada (Lindsay et al., 2004; Wolfson et al., 2001). In the first phase of the study, conducted from 1991 to 1992, 14026 subjects aged 65 or older were randomly selected from 36 urban and surrounding rural areas in 10 Canadian provinces. Among them, 10263 agreed to participate and were screened for dementia with the Modified Mini-Mental State Examination. Researchers identified 1132 subjects with dementia and classified them into subcategories of dementias. Our analysis is limited to subjects with a diagnosis of probable Alzheimer's disease, possible Alzheimer's disease, or vascular dementia. While there is no consensus regarding the association between dementia subtype and survival outcome, it is of great interest to estimate the survival distribution by each diagnosis type and investigate the association under a flexible model structure. Information about the date of onset of dementia was collected in a hierarchical fashion from the answers to three questions from the Cambridge Examination for Mental Disorders of the Elderly (Wolfson et al., 2001). In the second phase of the CSHA, conducted from 1996 to 1997, all participants who could be contacted were re-evaluated for dementia; subjects with dementia who died before and during the follow-up study were identified and the dates and causes of death were recorded. The third phase of the CSHA from 2001 to 2002 was generally the same as the second phase of the study. As expected, selection bias occurred under the described sampling circumstances: the observed time intervals from dementia diagnosis to death tended to be longer for subjects in the CSHA compared to those from subjects in the general (i.e., target) population. An analytic approach that ignores such selection bias could result in an overestimation of the survival duration for subjects with dementia, and consequently an underestimation of the deleterious effect of dementia on life expectancy. Moreover, the estimation of the association between dementia diagnoses and disease prognosis could be biased as well.

The paper is organized as follows. Section 2 introduces the notations and the semi-parametric AFT model. In Section 3, we propose two types of semi-rank-based regression methods to model length-biased right-censored data under the AFT model and describe the associated large sample properties of the estimators. We examine the performance of the proposed estimators through a simulation study in Section 4. We revisit the motivating example and present the analysis results of the CSHA in Section 5. We conclude with a discussion in Section 6, and provide details of the proofs in the Appendix.

2. Notations and Models

Consider the CSHA, in which subjects who were identified with dementia but had survived up to the time of recruitment were sampled and followed prospectively until death or censoring. Let $\tilde{T}$ be the unbiased time measured from onset of dementia to death in the target population, T be the observed length-biased time in the sample population, A be the time of recruitment measured from onset of dementia, V be the time from recruitment to death, and C be the residual censoring time measured from recruitment. Denote the covariate of interest as the p -vector $\mathbf{X}$. Conditional on $\mathbf{X}$, the residual censoring time C and (A, V) are assumed to be independent. Observed data are represented by n independent samples, $(Y_i, A_i, \delta_i, \mathbf{X}_i)$, where $Y_i = \min\{T_i, A_i + C_i\}$, $\delta_i = I(V_i - C_i)$ and $I(\cdot)$ is the indicator function here and in the sequel. Given the covariates, $\mathbf{X} = \mathbf{x}$, let $f(\cdot|\mathbf{x})$ represent the density function for the

unbiased time $\tilde{T}$. Under the sampling constraint that the value of $\tilde{T}$ is observed only when $\tilde{T} > A$, the density function of length-biased time T is

$$f_{LB}(t|\mathbf{x}) = \frac{tf(t|\mathbf{x})}{\int_0^\infty uf(u|\mathbf{x}) du} = \frac{tf(t|\mathbf{x})}{\mu(x)},$$

where $\mu(x) \equiv \int_0^\infty uf(u|\mathbf{x}) du$.

The AFT model (Kalbfleisch and Prentice, 1980; Cox and Oakes, 1984) relates the logarithms of the survival time to the covariate of interest through a linear form,

$$\log \tilde{T}_i = \mathbf{X}_i^T \beta + \epsilon_i, \quad (2.1)$$

where β is a $P \times 1$ parameter vector and $\epsilon_i, i = 1, \dots, n$ are independently and identically distributed (i.i.d.) random errors with an unspecified distribution.

3. Semi-rank-based Estimation Methods

For classical survival data, Tsiatis (1990) proposed a rank-based estimating equation by considering the transformed time scale under the AFT model. For left-truncated and right-censored data, Lai and Ying (1991b) introduced a class of rank-based estimators under the AFT model. Under length-biased sampling, the censoring time $A + C$ is mechanistically dependent on the failure time $A + V$ even if the censoring time C is independent of (A, V) . Hence, the generalizations of the above methods entail new challenges in order to adjust for non-informative censoring. The generalized methods will not only depend on the rank, but also rely on the magnitude of failure time for length-biased data.

3.1. Estimation Method Based on Modified Risk Set

For general left-truncated and right-censored data, Lai and Ying (1991b) constructed the at-risk set at time t as $R^*(t, \mathbf{b}) = \{i : A_i \exp(-\mathbf{X}_i^T \mathbf{b}) < t < Y_i \exp(-\mathbf{X}_i^T \mathbf{b})\}$, and proposed the rank-based estimating equations for β based on the constructed at-risk sets,

$$\mathbf{U}_{LT}(\beta) = \sum_{i=1}^n \delta_i \left[\mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j I\{j \in R^*(Y_i e^{-\mathbf{X}_i^T \beta}, \beta)\}}{\sum_{j=1}^n I\{j \in R^*(Y_i e^{-\mathbf{X}_i^T \beta}, \beta)\}} \right]. \quad (3.1)$$

This estimating equation, originally proposed for general left-truncated data, does not effectively utilize information on the truncation time and is consequently inefficient for length-biased data. Under the stationarity assumption for length-biased data, Tsai (2009) proposed the pseudo-partial likelihood method under Cox's proportional hazards model by including the information for the stationarity process. Under the AFT model assumption for $\tilde{T}$, we include the information on truncation time for length-biased data and modify this “at risk” set to increase the estimation efficiency. Given the observed data $(Y = y, \delta, \mathbf{X} = \mathbf{x})$, the conditional expectation of the indicator function of the “at risk” set is

$$\begin{aligned} R(y, t) &= E[I(A < t \leq Y) | \delta, Y = y, \mathbf{X} = \mathbf{x}] \\ &= \delta I(y \geq t) \frac{P(A < t, T = y, C \geq y - A | \mathbf{X} = \mathbf{x})}{P(T = y, C \geq y - A | \mathbf{X} = \mathbf{x})} + (1 - \delta) I(y \geq t) \frac{P(A < t, T \geq y, C = y - A | \mathbf{X} = \mathbf{x})}{P(T \geq y, C = y - A | \mathbf{X} = \mathbf{x})}. \end{aligned}$$

Using the fact that the bivariate distribution of (T, A) given $\mathbf{X} = \mathbf{x}$ is $f(t|\mathbf{x})/\mu(\mathbf{x})$ for $t > a > 0$,

$$R(y, t) = \delta I(y \geq t) \frac{f(y|x) \int_0^t \bar{G}(y-a|x) da / \mu(x)}{f(y|x) \int_0^y \bar{G}(y-a|x) da / \mu(x)} + (1-\delta) I(y \geq t) \frac{\int_y^\infty f(s|x) / \mu(x) ds \int_0^t g(y-a|x) da}{\int_y^\infty f(s|x) / \mu(x) ds \int_0^y g(y-a|x) da};$$

therefore

$$R(y, t) = \delta I(y \geq t) \frac{W(y|x) - W(y-t|x)}{W(y|x)} + (1-\delta) I(y \geq t) \frac{G(y|x) - G(y-t|x)}{G(y|x)},$$

where $G(\cdot|x)$, $\bar{G}(\cdot|x)$, and $g(\cdot|x)$ respectively are the cumulative distribution function, survival function, and density function for the residual censoring time given $\mathbf{X} = \mathbf{x}$, and $W(t|x)$ is the integral of the survival function of residual censoring time from 0 to t ,

$W(t|x) = \int_0^t \bar{G}(s|x) ds$. For notation brevity, we will remove $\mathbf{x}$ from the functions of G and W in the following derivations.

By modifying equation (3.1), we replace the indicator function for the at-risk set with the conditional expectation of the indicator function in (3.2). Note that information of the stationary process is utilized in the following constructed estimating equation:

$$\begin{aligned} \tilde{U}_I(\beta) &= \frac{1}{n} \sum_{i=1}^n \delta_i \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j R(Y_j e^{-\mathbf{X}_j^T \beta}, Y_i e^{-\mathbf{X}_i^T \beta})}{\sum_{j=1}^n R(Y_j e^{-\mathbf{X}_j^T \beta}, Y_i e^{-\mathbf{X}_i^T \beta})} \right\} \\ &= \frac{1}{n} \sum_{i=1}^n \int_0^\infty \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j R(Y_j e^{-\mathbf{X}_j^T \beta}, t)}{\sum_{j=1}^n R(Y_j e^{-\mathbf{X}_j^T \beta}, t)} \right\} dN_i(\beta, t), \end{aligned} \quad (3.2)$$

where $N_i(\beta, t) = I(Y_i e^{-\mathbf{X}_i^T \beta} \geq t, \delta_i = 1)$. Note that $\mathbf{X}$ is a categorical variable in the motivating example and the survival function of the censoring variable C can be estimated consistently for each of the three categories if the censoring distributions are not the same. Otherwise, G and W can be estimated using the pooled data. After plugging in the consistent estimators of the unknown quantities into $R(y, t)$,

$$\hat{R}(y, t) = \delta I(y \geq t) \frac{\hat{W}(y) - \hat{W}(y-t)}{\hat{W}(y)} + (1-\delta) I(y \geq t) \frac{\hat{G}(y) - \hat{G}(y-t)}{\hat{G}(y)},$$

where $\hat{G}(y)$ is the Kaplan-Meier estimator of the cumulative distribution function for the residual censoring variable and $\hat{W}(y) = \int_0^y \hat{G}(s) ds$. With the estimated $\hat{R}(y, t)$, we obtain the estimating equation for β ,

$$\mathbf{U}_I(\beta) = \frac{1}{n} \sum_{i=1}^n \int_0^\infty \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j \hat{R}(Y_j e^{-\mathbf{X}_j^T \beta}, t)}{\sum_{j=1}^n \hat{R}(Y_j e^{-\mathbf{X}_j^T \beta}, t)} \right\} dN_i(\beta, t). \quad (3.3)$$

The estimating equation (3.3) is not a continuous function of β , therefore, it is not always possible to obtain an exact solution to this estimating equation. We define a solution of equation (3.3), called $\hat{\beta}_I$, to be the minimizer of the Euclidean norm of $\mathbf{U}_I(\beta)$ (Wei et al.,

1990). Denote β_0 to be the true value of β . The consistency and weak convergence of $\hat{\beta}_I$ can be established under the regularity conditions listed in the Appendix.

Theorem 1 Under assumptions A.1–A.5 in the Appendix, $\hat{\beta}_I$ is a consistent estimator of β_0 and $\sqrt{n}(\hat{\beta}_I - \beta_0)$ converges weakly to a normal distribution with mean zero and variance-covariance matrix Σ_I .

The variance-covariance matrix Σ_I in Theorem 1 is defined in the Appendix. The asymptotic normality of $\sqrt{n}(\hat{\beta}_I - \beta_0)$ is derived by using the asymptotic linearity of the estimating equation $U_I(\beta)$ and the empirical process theory. The detailed proof of Theorem 1 is provided in the Appendix. The estimation of the variance-covariance matrix Σ_I is not straightforward because of the unknown hazard function in Σ_I . Given the established weak convergence of $\hat{\beta}_I$, we will use the bootstrap resampling method to approximate the variance of $\hat{\beta}_I$.

3.2. Estimation Equation Based on Inverse Weighting and Ranking

In the absence of right censoring, Wang (1996) derived the following score estimating equation from the pseudo-likelihood function under Cox's proportional hazards model:

$$\frac{1}{n} \sum_{i=1}^n \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j e^{\mathbf{X}_j^T \beta} I(T_j \geq T_i) / T_j}{\sum_{j=1}^n e^{\mathbf{X}_j^T \beta} I(T_j \geq T_i) / T_j} \right\} = 0. \quad (3.4)$$

Under the AFT model assumption for $\tilde{T}$ in (2.1), the transformed data $\tilde{T}_0 \equiv \tilde{T} e^{-\mathbf{X}^T \beta}$ are i.i.d. and the AFT model (2.1) can be equivalently expressed by Cox's proportional hazards model with no covariate effects (Tsiatis, 1990),

$$\lambda_{\tilde{T}_0}(t) = \lambda_0(t),$$

where $\lambda_0(t)$ is an unspecified hazard function of e^ϵ . We can thus generalize estimating equation (3.4) under Cox's model to the AFT model with the transformed length-biased data,

$$\frac{1}{n} \sum_{i=1}^n \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j I(T_j e^{-\mathbf{X}_j^T \beta} \geq T_i e^{-\mathbf{X}_i^T \beta}) / (T_j e^{-\mathbf{X}_j^T \beta})}{\sum_{j=1}^n I(T_j e^{-\mathbf{X}_j^T \beta} \geq T_i e^{-\mathbf{X}_i^T \beta}) / (T_j e^{-\mathbf{X}_j^T \beta})} \right\} = 0. \quad (3.5)$$

In the presence of potential right censoring to length-biased data, only $Y = \min\{T, A + C\}$ and the corresponding censoring indicator are observed. Qin and Shen (2010) proposed the following estimating equation to accommodate the dependent right censoring under Cox's proportional hazards model:

$$\frac{1}{n} \sum_{i=1}^n \delta_i \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j e^{\mathbf{X}_j^T \beta} \delta_j I(Y_j \geq Y_i) / \widehat{W}(Y_j)}{\sum_{j=1}^n e^{\mathbf{X}_j^T \beta} \delta_j I(Y_j \geq Y_i) / \widehat{W}(Y_j)} \right\},$$

where $\widehat{W}(t) = \int_0^t \widehat{G}(s) ds$ is a consistent estimator of $W(t)$. Using a technique parallel to that of Qin and Shen (2010) under the proportional hazards model, we construct an estimating equation under the AFT model as follows,

$$\begin{aligned}
U_{II}(\beta) &= \frac{1}{n} \sum_{i=1}^n \delta_i \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j \delta_j I(Y_j e^{-\mathbf{X}_j^T \beta} \geq Y_i e^{-\mathbf{X}_i^T \beta}) / \widehat{W}(Y_j e^{-\mathbf{X}_j^T \beta})}{\sum_{j=1}^n \delta_j I(Y_j e^{-\mathbf{X}_j^T \beta} \geq Y_i e^{-\mathbf{X}_i^T \beta}) / \widehat{W}(Y_j e^{-\mathbf{X}_j^T \beta})} \right\} \\
&= \frac{1}{n} \sum_{i=1}^n \left\{ \mathbf{X}_i - \frac{\sum_{j=1}^n \mathbf{X}_j \delta_j I(Y_j e^{-\mathbf{X}_j^T \beta} \geq t) / \widehat{W}(Y_j e^{-\mathbf{X}_j^T \beta})}{\sum_{j=1}^n \delta_j I(Y_j e^{-\mathbf{X}_j^T \beta} \geq t) / \widehat{W}(Y_j e^{-\mathbf{X}_j^T \beta})} \right\} dN_i(\beta, t)
\end{aligned} \quad (3.6)$$

As Equation (3.6) is a step function of β , we define a solution of this equation, called $\widehat{\beta}_{II}$, to be the minimizer of the Euclidean norm of $U_{II}(\beta)$. The consistency and weak convergence of $\widehat{\beta}_{II}$ can be established under the regularity conditions listed in the Appendix.

Theorem 2 Under assumptions A.1–A.5 in the Appendix, $\widehat{\beta}_{II}$ is a consistent estimator of β_0 and $\sqrt{n}(\widehat{\beta}_{II} - \beta_0)$ converges weakly to a normal distribution with mean zero and variance-covariance matrix Σ_{II} .

4. Simulation

We explored the finite sample properties of the two semi-rank-based proposed estimators ($\widehat{\beta}_I$ and $\widehat{\beta}_{II}$) via simulation studies. We compared the two proposed estimators with estimators by three existing methods: the inverse weighted estimating equation U_{IW} by Shen et al. (2009), the Buckley-James-type estimating equation U_{BJ} by Ning et al. (2011), and the rank-based estimating equation (3.1) by Lai and Ying (1991b) for general left-truncated data, which are specified as follows:

$$U_{IW}(\beta) = \frac{1}{n} \sum_{i=1}^n \frac{\delta_i \mathbf{X}_i}{\widehat{W}(Y_i)} (\log Y_i - \mathbf{X}_i^T \beta) = 0, \quad (4.1)$$

$$U_{BJ}(\beta) = \frac{1}{n} \sum_{i=1}^n \mathbf{X}_i \left\{ \delta_i \frac{\log Y_i - \mathbf{X}_i^T \beta}{Y_i \exp(-\mathbf{X}_i^T \beta)} + (1 - \delta_i) \frac{\int_{Y_{i0}}^{\infty} u^{-1} \log u d\widehat{F}_0(u; \beta)}{1 - \widehat{F}_0(Y_{i0}; \beta)} \right\}, \quad (4.2)$$

where

$$\widehat{F}_0(t; \beta) = \frac{\int_0^t s^{-1} d\widehat{G}_0(s; \beta)}{\int_0^{\infty} s^{-1} d\widehat{G}_0(s; \beta)}$$

is the consistent estimate of the unbiased distribution of transformed data $\widetilde{T}_0$, derived from Vardi's nonparametric estimate for the biased distribution of T_0 . We further investigated these semiparametric estimators and maximum likelihood estimator (MLE) in terms of the efficiency and the robustness with respects to the distribution assumption of the random error of with the MLE. Specifically, we derived the MLE under the assumption that the distribution of the random error follows a normal distribution, and then evaluated all estimators including the MLE under the assumption of normal distribution by using data generated from normal or uniform distributions.

We generated the unbiased failure times $\widetilde{T}_i$ from an AFT model with two covariates. The AFT model takes the form

$$\log(\tilde{T}_i) = \alpha_0 + \alpha_1 X_{1i} + \alpha_2 X_{2i} + \epsilon_i,$$

where X_{1i} is a binary covariate with $P(X_{1i} = 1) = 0.5$, and X_{2i} is a continuous covariate with a uniform(0,1) distribution. We set $\alpha_0 = 1$, $\alpha_1 = 0.5$, and $\alpha_2 = 1$. The ϵ_i s were generated either from a uniform $(-0.5, 0.5)$ distribution or from a Normal(0, 1/12) distribution. After taking exponential transformation, we have the unbiased survival times. The truncation times and residual censoring times were generated in the original time scale (not log-scale). Specifically, the truncation times were generated from a uniform distribution with an upper boundary bigger than the upper bound of $\tilde{T}$ to ensure the stationarity assumption. We kept only the pairs satisfying $A_i < \tilde{T}_i$. The residual censoring times, C_i , were independently generated from a uniform distribution over $(0, c)$, where c was chosen to yield the censoring percentage of 15%, 30%, or 50%. For each specified set of parameters, a sample size of 100 or 200 was chosen and each scenario was repeated 1000 times.

Table 4.1 displays the means and empirical standard errors of each estimator. From Table 4.1, we make the following observations: (i) All aforementioned estimators were close to the true values with mild or moderate censoring (15–30%), and the biases of $\hat{\beta}_I$ and $\hat{\beta}_{II}$ were slightly larger than those by the others, but all were in a reasonable range with heavy censoring (50%). (ii) $\hat{\beta}_I$ performed well as $\hat{\beta}_{II}$ with mild or moderate censoring (15–30%) and was less efficient with heavy censoring (50%), in particular when the random errors followed the normal distribution. (iii) As expected, the two proposed estimators were consistently more efficient than the estimators from U_{LT} for general left-truncated data regardless of the underlying distribution for the random errors. The unknown censoring distribution has to be estimated in the proposed estimating methods due to the unique data structure of length-biased data. The uncertainty from the estimated censoring distribution could result in a relative large bias for the proposed methods compared to the LT method. (iv) Under the normal distribution for the random errors, the estimators by U_{IW} performed as well as the two proposed estimators or better for heavy censoring, and U_{BJ} outperformed all other semi-parametric estimators with mild or moderate censoring (15–30%) in terms of efficiency. (iv) Under the uniform distribution for the random errors, the estimators from U_I and U_{II} consistently outperformed the other semiparametric estimators, whereas the estimators from U_{IW} and U_{BJ} were less efficient than the estimator from U_{LT} .

Table 4.2 compares the estimated relative efficiency of the six aforementioned estimators; the estimated relative efficiency was calculated as the ratio of two mean squared errors (MSEs) and the MSE of the estimator from U_{II} was used as a reference. From Table 4.2, we found that (i) when the censoring percentage increases, the efficiency gain of $\hat{\beta}_{II}$ relative to $\hat{\beta}_I$ increases; (ii) when the random error follows the uniform distribution, the proposed two estimators are much more efficient than the estimators from U_{IW} or U_{BJ} even with mild censoring, and the estimators from U_{LT} could be more efficient than those from U_{IW} or U_{BJ} ; (iii) when the error follows the normal distribution, using the Buckley-James method is more efficient than using the proposed methods except for with heavy censoring, and U_{LT} is the least efficient method. It is not surprising that the parametric MLE is the most efficient estimator when the error distribution is correctly specified in the likelihood. However, we also found (i) Compared with the MLE under correctly specified distribution assumption, the efficiency loss of the five semiparametric estimators is mild for length-biased data; (ii) The proposed two semiparametric estimators are much robust than the MLE with respect to the distribution assumption.

There is no uniform best estimation method in terms of statistical efficiency among the estimation methods considered in this paper. The order of statistical efficiency depends on the degree of censoring and the underlying distribution. When the distribution of $\log \tilde{T}$ is close to a normal distribution, the inverse weighted method and Buckley-James method, which are derived from the least squares principle, are more efficient than the two proposed semi-rank-based estimation methods. On the other hand, if the underlying distribution is uniform, the two proposed semi-rank-based estimation methods are better in terms of statistical efficiency. Fig.4.1 summarizes a decision guideline on the estimation methods for various combinations of underlying distribution and censoring patterns.

5. Data Application

Occurrence of dementia shortens life expectancy, and the accurate estimation of survival time could empower clinicians and patients with dementia to make timely decisions about their treatment. The CSHA is a national longitudinal study of Canadian people aged 65 years and over, focusing on prevalence and incidence of dementia. In the study, subjects with dementia were identified and classified into subcategories of dementia. Our goal was to estimate and compare survival following the onset of dementia according to the subcategory of dementia (Alzheimer's disease, possible Alzheimer's disease, or vascular dementia). The available data were collected from 818 subjects with dementia. Among them, 393 subjects were diagnosed as having probable Alzheimer's disease, 252 as having possible Alzheimer's disease, and 173 as having vascular dementia. For each subject, the date of dementia onset was collected during the clinical examination in the first stage of the CSHA (Wolfson et al. 2001), and the date of censoring or death was collected prospectively during the second or third phase of the CSHA. As mentioned, subjects who died quickly after dementia onset were more likely to be excluded (left truncated) from the study and, in turn, the observed survival duration from dementia onset in the prevalent cohort tended to be longer than that in the target population. Hence, in such a situation, adjustment of biased sampling is important to avoid an overestimation of survival for patients with dementia.

Wolfson et al. (2001) provided a figure that included three estimated survival functions according to diagnosis of subcategory of dementia, using the Expectation Maximization(EM) algorithm proposed by Vardi (1989) for length-biased and right-censored data. The figure suggested there may be some differences among the three subgroups; however, the one sample estimation could not answer if such differences are statistically significant or not. We applied the proposed inference methods under the accelerated failure time model $\log \tilde{T} = \alpha_0 + \alpha_1 X_1 + \alpha_2 X_2 + \epsilon$ to evaluate the effects of different diagnostic subcategories of dementia on survival, where X_1 and X_2 indicate whether the subject had vascular dementia or probable Alzheimer's disease, respectively.

The stationarity assumption that the truncation time is uniformly distributed was examined using the formal test given by Addona and Wolfson (2006). The test gave a p-value of 0.94, suggesting that the observed left-truncated data were length-biased data. The applicability of the AFT time to the application was checked using QQ-plots (Ning et al., 2011). We checked the underlying distributions of $\log \tilde{T}$ for three subgroups by comparing the nonparametric estimators of survival distributions (Vardi, 1989) and normal survival distributions. The plots shown in Fig.5.2 suggest that the underlying distributions of survival duration from dementia onset are close to normal distributions. Considering the censoring degrees among the three groups (20% ~ 24%) in this study, the Buckley-James method should be a good choice among the estimation methods considered in this paper. However, for comparison, all estimated results, including the proposed two estimators, the three estimators by equations U_{IW} , U_{BJ} , and U_{LT} , and the corresponding bootstrap standard errors, are listed in Table 5.3.

The estimators and inference from the five estimating methods with adjustment for length-biased sampling were comparable. The results indicate a trend for shorter survival time for the category of vascular dementia, though the difference was not statistically significant. Among the estimation methods applied to the study, the estimator from the proposed estimating equation U_{II} had a smaller variation standardized by dividing the size of the estimator than the estimators from the other estimating equations. Estimators obtained from the estimating equations U_I , U_{IW} , and U_{BJ} were fairly comparable.

6. Discussion

In this article, we have introduced two estimation methods for right-censored length-biased data under the AFT model. Besides the straightforward interpretation of the parameters, another appealing feature of the AFT model is that the observed failure time data can be transformed to a different time scale so that the transformed samples are i.i.d. without the covariate effect. This facilitates the use of existing estimating equations proposed for Cox's proportional hazards model or other rank-based estimating equations after some modifications. In contrast to the existing rank-based approaches (Lai and Ying, 1991b; Tsiatis, 1990), the proposed semi-rank-based methods rely on both the magnitude and the rank of failure times in the estimating equations. For example, the weights in the “at-risk” function of U_I are related to the magnitude of failure times. In the two proposed methods, the intercept in the AFT model is not estimated and the inference focus is on the slope parameters. If it is of interest to estimate the intercept in the AFT model, the inverse weighted method of (Shen et al., 2009) can be easily adapted for this purpose.

Of note, censoring distribution is often considered as a nuisance quantity when analyzing traditional survival data assuming non-informative censoring. Due to the informative censoring caused by biased sampling, the distribution of the censoring variable plays an important role in the construction of both estimating equations.

In this paper, we also compared the performance of the two proposed methods with three existing methods in empirical studies. The inverse weighted estimating equation approach (Shen et al., 2009) is the most computationally efficient with a simple closed form of the solution, but it is not the most statistically efficient in general. There is no uniform most efficient estimation method among the five investigated methods. The estimation efficiency depends on the underlying distribution and censoring patterns. In general, if the log-transformed failure times follow a normal distribution, the least squares or weighted least squares based methods should be more efficient. On the other hand, if the underlying distribution of log-transformed times is uniform or exponential, the rank-based methods should be a better choice.

We have restricted our attention to the setting with covariate-independent censoring. The Buckley-James estimator is robust to this assumption, since it does not require an estimate of the survival function for the censoring but imputing for the corresponding information. The two proposed semi-rank-based estimators can be easily generalized by including covariate-dependent weights in the estimating equations when C dependent on X , given that the conditional distribution $(G(t|X))$ can be estimated consistently using nonparametric or semi-parametric methods. One advantage of the two proposed estimators over the Buckley-James estimator is that there is no need to use a consistent estimator as an initial value in the iterative estimation algorithms. As a result, the variances of the two proposed estimators do not depend on the the initial estimator.

Our work is based on the length-biased density function conditional on the covariates X . There are some discussions on efficiency loss in literature, when using likelihood

conditional on the covariates for length-biased data (Bergeron et al., 2008; Mandel and Ritov, 2010). Specifically, there can be a loss of efficiency for the proposed estimator conditional on the covariates, when the marginal distribution of covariates is known (Bergeron et al., 2008). However, there is no loss of efficiency for the estimators based on the likelihood conditional on X , if the marginal distribution of the covariates is unknown, which is common in applications. Extending the AFT model to include time dependent covariates is nontrivial for length-biased data, due in part to the sampling mechanism. The necessary developments for this important extension are worthy of future research and are beyond the scope of this paper.

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Appendix

We assume the following regularity conditions:

- (A.1) $\mathbf{X}$ is uniformly bounded by M_X , and if there exists a constant vector c such that $c^T \mathbf{X} = 0$ with probability one, then $c = 0$.
- (A.2) The parameter space of β , $\mathbf{B}$, is a compact set including the true value of parameter β_0 .
- (A.3) $\tau = \inf\{t : F_0(t) = 1\} < \infty$, where $F_0(t)$ is the cumulative density function of $\tilde{T}_0$.
- (A.4) The density function of $\tilde{T}_0$, f_0 , is a continuous and differentiable distribution function over $(0, \tau)$, and its derivative f'_0 is bounded.
- (A.5) The residual censoring time has a uniformly bounded density g .

Since the semi-rank-based estimating equations are not continuous functions of β , Taylor's expansion theorem is not applicable here. Following the arguments for asymptotic properties of linear rank-based estimators (Ying, 1993) for right-censored data, we show the consistency and asymptotic normality of $\hat{\beta}_I$ and $\hat{\beta}_{II}$.

Proof of Theorem 1

$$\text{Let } \bar{N}^x(\mathbf{b}, t) = \frac{1}{n} \sum_{i=1}^n \mathbf{X}_i N_i(\mathbf{b}, t), \bar{N}(\mathbf{b}, t) = \frac{1}{n} \sum_{i=1}^n N_i(\mathbf{b}, t), \\ \bar{R}(\mathbf{b}, t) = \frac{1}{n} \sum_{i=1}^n \hat{R}(Y_i e^{-\mathbf{X}_i^T \mathbf{b}}, t), \text{ and } \bar{R}^x(\mathbf{b}, t) = \frac{1}{n} \sum_{i=1}^n \mathbf{X}_i \hat{R}(Y_i e^{-\mathbf{X}_i^T \mathbf{b}}, t).$$

Define the “mean function” for the estimating equation $\mathbf{U}_I(\mathbf{b})$

$$\mathbf{m}_I(\mathbf{b}) = E \left[\int_0^\infty \left\{ \mathbf{X} - \frac{E \mathbf{X} \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)}{E \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)} \right\} dN(\mathbf{b}, t) \right].$$

For any $N_b > 0$,

$$\begin{aligned} \sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \|\mathbf{U}_I(\mathbf{b}) - \mathbf{m}_I(\mathbf{b})\| &\leq \sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \|E \int_0^\infty \mathbf{X} dN(\mathbf{b}, t) \\ &\quad - \int_0^\infty d\bar{N}^x(\mathbf{b}, t)\| + \sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \left\| \int_0^\infty \frac{\bar{R}^x(\mathbf{b}, t)}{\bar{R}(\mathbf{b}, t)} d \left\{ EN(\mathbf{b}, t) - \bar{N}(\mathbf{b}, t) \right\} \right\| \\ &\quad + \sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \left\| \int_0^\infty \left\{ \frac{E \mathbf{X} \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)}{E \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)} - \frac{\bar{R}^x(\mathbf{b}, t)}{\bar{R}(\mathbf{b}, t)} \right\} dEN(\mathbf{b}, t) \right\|. \end{aligned} \quad (7.1)$$

For any $\epsilon > 0$, applying Lemma 1 in Ying (1993) which says the order of the weighted empirical process centered at its mean,

$$\sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \|E \int_0^\infty \mathbf{X} dN(\mathbf{b}, t) - \int_0^\infty d\bar{N}^x(\mathbf{b}, t)\| = o(n^{-1/2+\epsilon}) \text{ a.s.}$$

The second term on the right side of equation (7.1) is $o(n^{-1/2+\epsilon})$ by applying the integration by parts and that fact that the total variation

$$\sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \left| \int_0^\infty d \frac{\bar{R}^x(\mathbf{b}, t)}{\bar{R}(\mathbf{b}, t)} \right| \leq p M_x \int_0^\infty \frac{-d \bar{R}(\mathbf{b}, t)}{\bar{R}(\mathbf{b}, t)} = O(\log n),$$

where $\int |dv(t)|$ of a vector function $v(t)$ denotes the sum of the total variations of all its components and p is the dimension of $\mathbf{X}$.

Note that

$$\left\| \frac{E \mathbf{X} \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)}{E \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)} - \frac{\bar{R}^x(\mathbf{b}, t)}{\bar{R}(\mathbf{b}, t)} \right\| \leq \frac{\|E \mathbf{X} \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t) - \bar{R}^x(\mathbf{b}, t)\|}{E \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)} + \frac{\|E \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t) - \bar{R}(\mathbf{b}, t)\|}{E \hat{R}(Y e^{-\mathbf{X}^T \mathbf{b}}, t)},$$

the third term on the right side of equation (7.1) is also $o(n^{-1/2+\epsilon})$.

Hence, for any $\epsilon > 0$

$$\sup_{\|\mathbf{b}-\beta_0\|\leq N_b} \|\mathbf{U}_I(\mathbf{b}) - \mathbf{m}(\mathbf{b})\| = o(n^{-1/2+\epsilon}) \text{ a.s.} \quad (7.2)$$

This implies that the estimating equation $\mathbf{U}_I(\mathbf{b})$ can be uniformly approximated by the nonrandom function $\mathbf{m}_I(\mathbf{b})$ up to the order of $n^{-1/2+\epsilon}$. If the function $\mathbf{m}_I(\mathbf{b})$ has a unique solution given a compact region $\mathbf{B}$ containing β_0 as an interior point, the estimator $\hat{\beta}_I$, which satisfies $\mathbf{U}_I(\hat{\beta}_I) = \min_{\mathbf{b} \in \mathbf{B}} \|\mathbf{U}_I(\mathbf{b})\|$, is strongly consistent. As discussed in Ying (1993), this assumption can be evaluated for any given joint distribution of $(\tilde{\mathbf{J}}, C, \mathbf{X})$. Denote the slope of function $\mathbf{m}_I(\mathbf{b})$ to be $\Gamma_I(\mathbf{b})$, where

$$\Gamma_I(\mathbf{b}) = -E \left[\int_0^\infty \mathbf{X}^T \left\{ \mathbf{X} - \frac{E \mathbf{X} \hat{R}(\eta(\mathbf{b}), t)}{E \hat{R}(\eta(\mathbf{b}), t)} \right\} e^{-\mathbf{X}^T \mathbf{b}} \left\{ f'_0(t(\mathbf{b})) W(t(\mathbf{b})) + f_0(t(\mathbf{b})) \bar{G}(t(\mathbf{b})) g(t(\mathbf{b})) \right\} dt \right]$$

, $\eta(\mathbf{b}) = Y e^{-\mathbf{X}^T \mathbf{b}}$ and $t(\mathbf{b}) = t e^{-\mathbf{X}^T \mathbf{b}}$.

The mean function $\mathbf{m}_I(\mathbf{b})$ is a continuous function. By Taylor expansion, we have

$$\mathbf{m}_I(\mathbf{b}) = \Gamma_I(\mathbf{b} - \beta_0) + o(\mathbf{b} - \beta_0), \quad (7.3)$$

where $\Gamma_I = \gamma_I(\beta_0)$. Following equations (7.2) and (7.3), the estimating equation U_I is asymptotically linear, i.e., for $\mathbf{d}_n \rightarrow 0^+$ in probability,

$$\sup_{\|\mathbf{b} - \beta_0\| \leq \mathbf{d}_n} \|\mathbf{U}_I(\mathbf{b}) - \mathbf{U}_I(\beta_0) - \Gamma(\mathbf{b} - \beta_0)\| = o_p(n^{-1/2} + \|\mathbf{b} - \beta_0\|).$$

As $\hat{\beta}_I \rightarrow \beta_0$ a.s., we have

$$\sqrt{n} \mathbf{U}_I(\hat{\beta}_I) = \sqrt{n} \mathbf{U}_I(\beta_0) + \Gamma_I \sqrt{n} (\hat{\beta}_I - \beta_0) + o_p(1). \quad (7.4)$$

We next study the asymptotic properties of the estimating equations evaluated at the true values of parameter, $\mathbf{U}_I(\beta_0)$. Let $\hat{\epsilon}$ and ϵ represent the sample empirical mean and the limit of average expectation. Using these notations, estimating equation $\mathbf{U}_I(\beta)$ could be expressed as

$$\mathbf{U}_I(\beta) = \hat{\epsilon}[\mathbf{X} N(\beta, \tau)] - \int_0^\tau \frac{\hat{\epsilon}[\mathbf{X} \hat{R}(Y e^{-\mathbf{X}^T \beta}, t)]}{\hat{\epsilon}[\hat{R}(Y e^{-\mathbf{X}^T \beta}, t)]} d\hat{\epsilon}[N(\beta, t)]. \quad (7.5)$$

The function $R(y, t)$ is estimated by using the Kaplan-Meier estimator of the survival function for the censoring. The two estimators $\hat{\epsilon}[\mathbf{X} \hat{R}(Y e^{-\mathbf{X}^T \beta_0}, t)]$ and $\hat{\epsilon}[\hat{R}(Y e^{-\mathbf{X}^T \beta_0}, t)]$ respectively converge to the limits $\epsilon[\mathbf{X} R(Y e^{-\mathbf{X}^T \beta_0}, t)]$ and $\epsilon[R(Y e^{-\mathbf{X}^T \beta_0}, t)]$. By the central limit theorem for variables and processes,

$$\sqrt{n} \{ \hat{\epsilon}[\mathbf{X} N(\beta_0, \tau)] - \epsilon[\mathbf{X} N(\beta_0, \tau)] \}$$

converges weakly to a normal variable, W_1 , with mean zero, and

$$\sqrt{n} \{ \hat{\epsilon}[N(\beta_0, t)] - \epsilon[N(\beta_0, t)] \}$$

converges to a Gaussian process, $\mathscr{W}_2$. Furthermore, we can show that

$$\sqrt{n} \left\{ \hat{\epsilon}[\hat{R}(Y e^{-\mathbf{X}^T \beta_0}, t)] - \epsilon[R(Y e^{-\mathbf{X}^T \beta_0}, t)] \right\} = n^{-1/2} \sum_{i=1}^n \psi_{i1}(t; \beta_0) + o_p(1)$$

$$\sqrt{n} \left\{ \hat{\varepsilon} \left[\mathbf{X} \hat{R} \left(Y e^{-\mathbf{X}^T \beta_0}, t \right) \right] - \varepsilon \left[\mathbf{X} R \left(Y e^{-\mathbf{X}^T \beta_0}, t \right) \right] \right\} = n^{-1/2} \sum_{i=1}^n \psi_{i2}(t; \beta_0) + o_p(1).$$

By the central limit theorem and the above two i.i.d. representations, the two processes converge weakly to Gaussian processes $\mathcal{W}_3$ and $\mathcal{W}_4$, respectively. Under the regularity conditions, the mapping of $\mathbf{U}_I(\beta_0)$ from the four processes is compactly differentiable with respect to the supremum norm. We therefore apply the functional delta method and establish the asymptotic i.i.d. representation of equation $\mathbf{U}_I(\beta_0)$,

$$n^{1/2} \mathbf{U}_I(\beta_0) = n^{-1/2} \sum_{i=1}^n \psi_{Ii}(\beta_0) + o_p(1), \text{ where}$$

where

$$\begin{aligned} \psi_{Ii}(\beta_0) &= \mathbf{X}_i N_i(\beta_0, \tau) \\ &\quad - \varepsilon[\mathbf{X} N(\beta_0, \tau)] \\ &\quad + \int_0^\tau \frac{\psi_{i1}(t; \beta_0) \varepsilon[\mathbf{X} R(Y e^{-\mathbf{X}^T \beta_0}, t)]}{\varepsilon[R(Y e^{-\mathbf{X}^T \beta_0}, t)]^2} d\varepsilon[N(\beta_0, t)] \\ &\quad - \int_0^\tau \frac{\psi_{i2}(t; \beta_0)}{\varepsilon[R(Y e^{-\mathbf{X}^T \beta_0}, t)]} d\varepsilon[N(\beta_0, t)] \\ &\quad - \int_0^\tau \frac{\varepsilon[\mathbf{X} R(Y e^{-\mathbf{X}^T \beta_0}, t)]}{\varepsilon[R(Y e^{-\mathbf{X}^T \beta_0}, t)]} d(N_i(\beta_0, \tau) - \varepsilon[N(\beta_0, t)]). \end{aligned}$$

Following this representation and equation (7.4),

$$\sqrt{n}(\hat{\beta}_I - \beta_0) = \Gamma_I^{-1} n^{-1/2} \sum_{i=1}^n \psi_{Ii}(\beta_0) + o_p(1).$$

Thus the desired asymptotic normality of $\hat{\beta}_I$ follows from the classical central limit theorem; $\sqrt{n}(\hat{\beta}_I - \beta_0)$ converges to a normal variables with mean zero and variance $\Sigma_I = \Gamma_I^{-1} \Sigma_{UI} \Gamma_I^{-1}$ where $\Sigma_{UI} = E[\psi_{UI}(\beta_0)]^{\otimes 2}$.

Proof of Theorem 2

By arguments similar to those in the proof of Theorem 1, we can show the asymptotic behavior of $\hat{\beta}_{II}$. We only give key steps here. The estimating equation $\mathbf{U}_{II}(\mathbf{b})$ can be shown to be uniformly approximated by the nonrandom function $\mathbf{m}_{II}(\mathbf{b})$ up to the order of $n^{-1/2+\epsilon}$, where

$$\mathbf{m}_{II}(\mathbf{b}) = E \left[\int_0^\infty \left\{ \mathbf{X} - \frac{E\mathbf{X} \delta I(\eta(\mathbf{b}) \geq t) / \widehat{W}(\eta(\mathbf{b}))}{E\delta I(\eta(\mathbf{b}) \geq t) / \widehat{W}(\eta(\mathbf{b}))} \right\} dN(\mathbf{b}, t) \right].$$

If the function $\mathbf{m}_{II}(\mathbf{b})$ has a unique solution given a compact region $\mathbf{B}$ containing β_0 as an interior point, the estimator $\hat{\beta}_{II}$ is strongly consistent. The slope function of $\mathbf{m}_{II}(\mathbf{b})$ is

$$\Gamma_{II}(\mathbf{b}) = - \int_0^\infty \mathbf{X}^T \left\{ \mathbf{X} - \frac{E\mathbf{X}\delta I(\eta(\mathbf{b}) \geq t) / \widehat{W}(\eta(\mathbf{b}))}{E\delta I(\eta(\mathbf{b}) \geq t) / \widehat{W}(\eta(\mathbf{b}))} \right\} e^{-\mathbf{X}^T \mathbf{b}} \\ \times \left\{ f'_0(t(\mathbf{b})) W(t(\mathbf{b})) + f_0(t(\mathbf{b})) \bar{G}(t(\mathbf{b})) g(t(\mathbf{b})) \right\} dt.$$

Furthermore, the estimating equation $\mathbf{U}_{II}$ is asymptotically linear and

$$\sqrt{n}\mathbf{U}_{II}(\hat{\beta}_{II}) = \sqrt{n}\mathbf{U}_{II}(\beta_0) + \Gamma_{II} \sqrt{n}(\hat{\beta}_{II} - \beta_0) + o_p(1), \quad (7.6)$$

where $\hat{\beta}_{II} = \Gamma_{II}(\beta_0)$. Similarly, using the functional delta method, we can establish the asymptotic i.i.d. representation of equation $\mathbf{U}_{II}(\beta_0)$, denoted as

$n^{1/2}\mathbf{U}_{II}(\beta_0) = n^{-1/2} \sum_{i=1}^n \psi_{IIi}(\beta_0) + o_p(1)$. Then the classical central limit theorem implies that $\sqrt{n}(\hat{\beta}_{II} - \beta_0)$ converges to a normal variable with mean zero and variance $\Sigma_I I = \Gamma_{II}^{-1} \Sigma_{UII} \Gamma_{II}^{-1}$, where $\Sigma_{UII} = E[\psi_{IIi}(\beta_0)]^{\otimes 2}$.

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Figure 4.1.
Decision Tree Plot of the Estimation Method Selection for Length-biased Data

Figure 5.2.
Plot of estimated survival functions according to the subcategory of dementia

Table 4.1

Summary statistics for six estimators

Size	Cen%	U _I Estimator			U _{IT} Estimator			U _{JW} Estimator			U _{RJ} Estimator			U _{IT} Estimator			Parametric MLE		
$(\hat{\alpha}_1, \hat{\alpha}_2)$																			
$\in \sim U(-0.5, 0.5)$																			
100	15%	(.006, .012)	(.044, .079)	(-.004, -.006)	(.044, .079)	(.044, .079)	(-.007, -.005)	(.070, .122)	(.000, .002)	(.068, .121)	(.002, .001)	(.051, .092)	(-.011, -.018)	(.064, .113)					
100	30%	(-.008, -.029)	(.052, .094)	(.008, .027)	(.051, .095)	(.051, .095)	(-.007, -.006)	(.073, .136)	(-.005, -.001)	(.067, .120)	(.001, -.006)	(.059, .117)	(-.028, -.053)	(.071, .125)					
100	50%	(.029, .039)	(.073, .164)	(-.018, -.033)	(.070, .127)	(.070, .127)	(-.008, -.005)	(.087, .157)	(.015, .036)	(.106, .190)	(.000, -.060)	(.078, .187)	(-.043, -.086)	(.082, .151)					
200	15%	(.005, .011)	(.027, .049)	(-.003, -.007)	(.027, .049)	(.027, .049)	(-.003, .000)	(.050, .087)	(.001, -.001)	(.048, .080)	(.001, -.001)	(.031, .054)	(-.011, -.020)	(.047, .082)					
200	30%	(.014, .028)	(.032, .059)	(-.011, -.025)	(.032, .062)	(.032, .062)	(-.003, -.005)	(.050, .094)	(.000, .002)	(.048, .086)	(.001, -.003)	(.037, .067)	(-.026, -.051)	(.050, .087)					
200	50%	(.030, .057)	(.043, .098)	(-.013, -.028)	(.042, .078)	(.042, .078)	(.000, .000)	(.058, .107)	(.015, .036)	(.066, .120)	(.001, -.014)	(.046, .102)	(-.046, -.080)	(.059, .102)					
$\in \sim Normal(0, 1/12)$																			
100	15%	(.014, .019)	(.072, .124)	(-.006, -.019)	(.073, .121)	(.073, .121)	(-.002, -.011)	(.073, .124)	(-.001, -.002)	(.072, .118)	(.004, -.004)	(.086, .138)	(-.012, -.023)	(.067, .115)					
100	30%	(.025, .045)	(.079, .133)	(-.018, -.043)	(.076, .136)	(.076, .136)	(-.002, -.013)	(.076, .134)	(.001, -.005)	(.067, .123)	(.001, -.014)	(.093, .151)	(-.027, -.052)	(.070, .124)					
100	50%	(.043, .050)	(.099, .198)	(-.029, -.044)	(.087, .162)	(.087, .162)	(-.003, -.012)	(.087, .160)	(-.030, -.065)	(.097, .186)	(-.002, -.060)	(.104, .183)	(-.044, -.081)	(.083, .140)					
200	15%	(.010, .019)	(.051, .089)	(-.010, -.024)	(.049, .088)	(.049, .088)	(-.002, -.011)	(.051, .086)	(-.001, -.001)	(.049, .081)	(.000, -.003)	(.060, .097)	(-.009, -.022)	(.047, .084)					
200	30%	(.024, .044)	(.056, .098)	(-.021, -.044)	(.051, .096)	(.051, .096)	(-.002, -.012)	(.054, .093)	(-.001, .002)	(.050, .085)	(-.001, -.006)	(.063, .106)	(-.025, -.053)	(.051, .089)					
200	50%	(.039, .084)	(.072, .135)	(-.028, -.031)	(.060, .116)	(.060, .116)	(-.002, -.009)	(.059, .111)	(-.030, -.052)	(.065, .121)	(-.003, -.012)	(.070, .125)	(-.040, -.084)	(.059, .105)					

Table 4.2

Relative efficiency for six estimators

Cohort Size	Cen%	U_I Estimator	U_{IW} Estimator	U_{BJ} Estimator	U_{LT} Estimator	Parametric MLE
$\epsilon \sim U(-0.5, 0.5)$						
100	15%	(1.01, 1.02)	(2.54, 2.38)	(2.37, 2.33)	(1.33, 1.35)	(2.16, 2.09)
100	30%	(1.04, 0.99)	(2.02, 1.90)	(1.69, 1.48)	(1.31, 1.41)	(2.18, 1.89)
100	50%	(1.18, 1.65)	(1.46, 1.43)	(2.19, 2.17)	(1.16, 2.24)	(1.64, 1.77)
200	15%	(1.02, 1.03)	(3.40, 3.09)	(3.12, 2.61)	(1.30, 1.19)	(3.16, 2.91)
200	30%	(1.07, 0.95)	(2.19, 1.98)	(2.01, 1.66)	(1.20, 1.01)	(2.77, 2.27)
200	50%	(1.42, 1.87)	(1.74, 1.67)	(2.37, 2.29)	(1.10, 1.54)	(2.90, 2.45)
$\epsilon \sim Normal(0, 1/12)$						
100	15%	(1.00, 1.05)	(0.99, 1.03)	(0.97, 0.93)	(1.38, 1.27)	(0.86, 0.92)
100	30%	(1.13, 0.97)	(0.95, 0.89)	(0.74, 0.74)	(1.42, 1.13)	(0.92, 0.89)
100	50%	(1.47, 1.48)	(0.96, 0.91)	(1.30, 1.38)	(1.36, 1.32)	(1.11, 0.93)
200	15%	(1.08, 1.00)	(1.04, 0.90)	(0.96, 0.79)	(1.44, 1.13)	(0.91, 0.91)
200	30%	(1.22, 1.03)	(0.96, 0.79)	(0.82, 0.65)	(1.31, 1.01)	(1.06, 0.96)
200	50%	(1.53, 1.75)	(0.79, 0.86)	(1.17, 1.20)	(1.12, 1.09)	(1.16, 1.25)

Table 5.3

Estimates (Est) and standard errors (SE) of regression coefficients for dementia data

	U_I Estimator	U_{II} Estimator	U_{IW} Estimator	U_{BJ} Estimator	U_{LT} Estimator
	Est(SE)	Est(SE)	Est(SE)	Est(SE)	Est(SE)
Vascular					
Dementia	-.152(.114)	-.156(.083)	-.210(.112)	-.187(.128)	-.106(.076)
Probable					
Alzheimer	-.138(.118)	-.102(.057)	-.135(.151)	-.114(.150)	-.033(.063)