

Benchmark map of forest carbon stocks in tropical regions across three continents

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Developing countries are required to produce robust estimates of forest carbon stocks for successful implementation of climate change mitigation policies related to reducing emissions from deforestation and degradation (REDD). Here we present a “benchmark” map of biomass carbon stocks over 2.5 billion ha of forests on three continents, encompassing all tropical forests, for the early 2000s, which will be invaluable for REDD assessments at both project and national scales. We mapped the total carbon stock in live biomass (above- and belowground), using a combination of data from 4,079 in situ inventory plots and satellite light detection and ranging (Lidar) samples of forest structure to estimate carbon storage, plus optical and microwave imagery (1-km resolution) to extrapolate over the landscape. The total biomass carbon stock of forests in the study region is estimated to be 247 Gt C, with 193 Gt C stored aboveground and 54 Gt C stored belowground in roots. Forests in Latin America, sub-Saharan Africa, and Southeast Asia accounted for 49%, 25%, and 26% of the total stock, respectively. By analyzing the errors propagated through the estimation process, uncertainty at the pixel level (100 ha) ranged from $\pm 6\%$ to $\pm 53\%$, but was constrained at the typical project (10,000 ha) and national ($>1,000,000$ ha) scales at ca. $\pm 5\%$ and ca. $\pm 1\%$, respectively. The benchmark map illustrates regional patterns and provides methodologically comparable estimates of carbon stocks for 75 developing countries where previous assessments were either poor or incomplete.

forest biomass | forest height | microwave and optical imaging | error propagation | carbon cycling

Deforestation and forest degradation, located primarily in tropical regions, accounted for 12–20% of global anthropogenic greenhouse gas (GHG) emissions in the 1990s and early 2000s (1–4) and these processes also impact the future potential of forests to remove additional carbon from the atmosphere (5–7). Estimates of GHG emissions from deforestation require information on both the area of forest loss and the corresponding carbon stock of the land that is cleared (8, 9). Both are considered challenging to quantify accurately (10). Much of the emphasis to date has focused on improving spatially represented estimates of forest area loss (11, 12). To improve confidence in estimated emissions, equal emphasis is needed on improving spatially explicit estimates of carbon stored in forests, which remain uncertain in tropical regions (13). The largest proportion of this uncertainty is in estimates of aboveground biomass (14, 15), which accounts for 70–90% of forest biomass carbon (16), and its spatial variability that depends on factors such as climate, human and natural disturbance and recovery, soil type, and topographical variations (14, 17). Reducing the uncertainty in emissions estimates requires temporally constrained estimates of forest carbon content at a spatial scale that is fine enough to capture the variability over the landscape and is quantified at the scale of disturbance affecting the forest. Such information would improve project- and national-level carbon stock estimates as well as assist in the development of baseline information re-

quired for reducing emissions from deforestation and degradation (REDD) activities designed to curb greenhouse gas emissions from the land use sector (15, 18).

Efforts to estimate the distribution of biomass rely on remote sensing techniques due to the wide geographical extent of forests, difficult accessibility, and the limited utility of field inventories owing to the natural spatial variability of forest biomass (8, 9, 14). New remote sensing approaches using light detection and ranging (Lidar) and radio detection and ranging (radar) from airborne sensors have been successful in providing high-resolution estimates of forest carbon density for small areas (19–21). However, the spaceborne sensors needed to use these approaches for large-scale mapping and monitoring efforts will not be available before the end of this decade (22). Until then, cost-effective mapping of carbon stocks for project- and national-scale assessments will rely on a combination of satellite imagery and ground-based inventory samples of forest carbon density (14, 21).

Here, we report on our use of global forest height data measured by the Geoscience Laser Altimeter System (GLAS), onboard the Ice, Cloud, and land Elevation Satellite (ICESat) (23), in combination with other remote sensing data bases and ground data, to model the spatial distribution of aboveground standing biomass density (AGB) (in megagrams of mass per unit area) in forests across three continental regions for the early 2000s. Our approach includes >3 million Lidar shots collected along the ICESat orbital tracks. For calibration of GLAS Lidar height to AGB and for validation of AGB distribution, we use AGB data from 4,079 available inventory and research plots distributed over the study region. We estimate belowground biomass carbon in roots from AGB using tree allometry (24). Our approach results in a benchmark map of forest carbon density at 1-km resolution. The accuracy of carbon estimates for every pixel is evaluated by propagating individual components of uncertainty through the spatial analysis.

Results

Relating Forest Height to Biomass. AGB estimates were compiled for 4,079 geo-referenced in situ forest plots (>0.1 ha) distributed over three continents and restricted to inventory dates between 1995 and 2005 (Fig. S1 and Table S1). Of these data, 493 calibration plots (298 in Latin America, 75 in Africa, and 120 in Southeast Asia) were located under the GLAS Lidar shots or within the same forest stands (Table S2). Data for these plots

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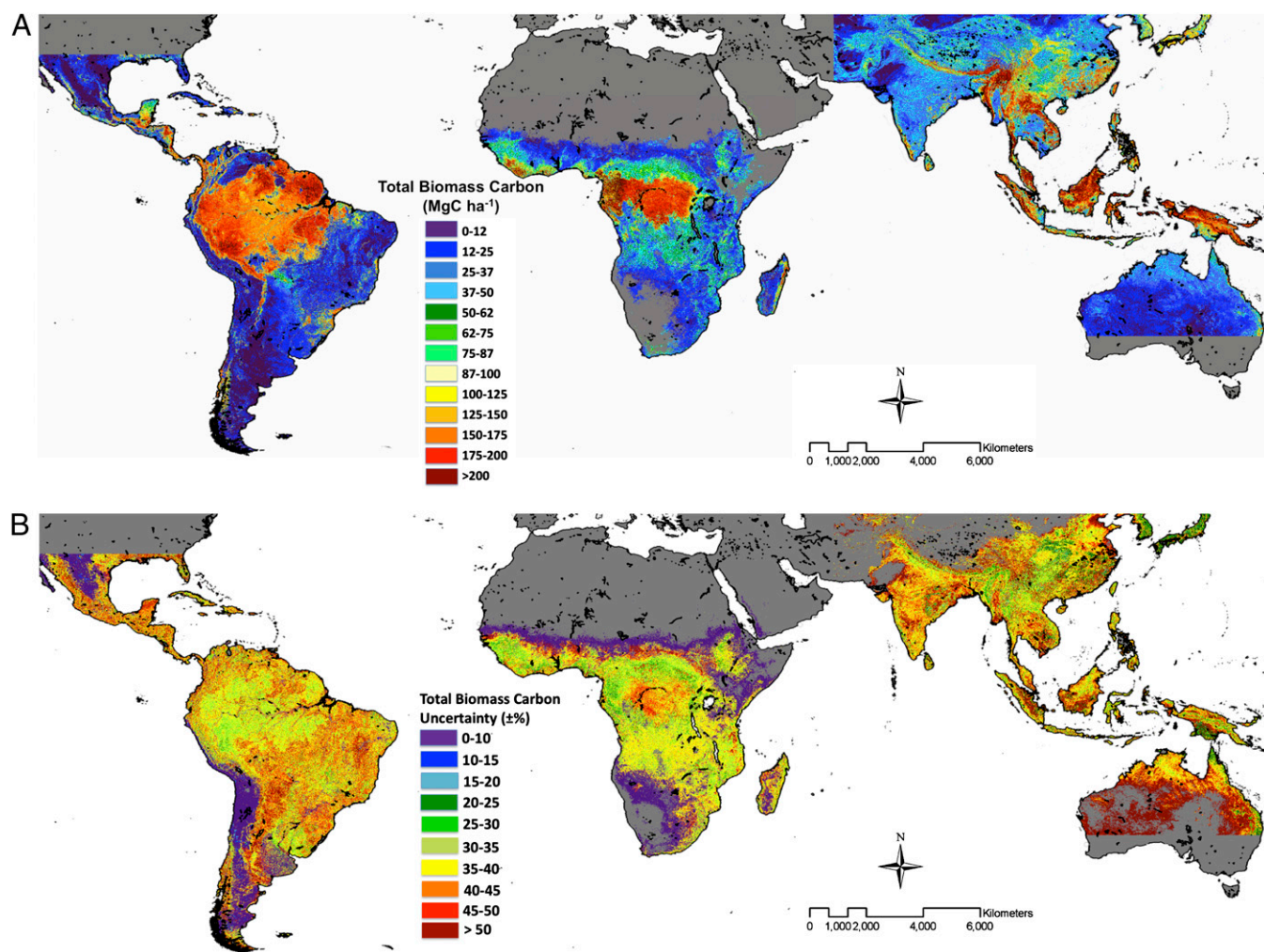


Fig. 3. Benchmark map of carbon stock and uncertainty. (A) Forest carbon stock defined as 50% of AGB + BGB is mapped at 1-km pixel resolution and colored on the basis of a 12–25 Mg C ha⁻¹ range to show the spatial patterns. (B) The uncertainty of the benchmark map is estimated using error propagation through a spatial modeling approach. The uncertainty is given in terms of plus or minus percent and it includes all errors associated with prediction from spatial modeling, estimation of Lorey's height from GLAS, estimation of AGB from Lorey's height, errors from pixel level variations, and errors associated with BGB estimation (*SI Materials and Methods*).

mates improve on forest carbon stock estimates reported previously (8, 13–15, 17, 18, 25) by providing a traceable and systematic approach to geographically locate the stock estimates for further monitoring and verification. The forest definitions chosen here using tree cover thresholds can readily change the estimates of total carbon and area-weighted carbon densities at national and regional scales.

Uncertainty Analysis. We assess the accuracy of the biomass carbon estimates by calculating the error as the difference between the true mean biomass value (bootstrapped samples of ground and Lidar-estimated AGB) and the predicted biomass value (mapped at 1-km grid cell resolution) and propagating these errors through the spatial modeling process (*SI Materials and Methods*). Errors in the distribution of forest aboveground biomass can be random or systematic in nature and can include the following: (i) *observation errors* associated with the uncertainty in estimates of Lorey's height from GLAS Lidar, errors associated with estimating AGB derived from GLAS Lidar height, and errors in estimating BGB from AGB (27); (ii) *sampling errors* associated with the spatial variability of AGB within a 1-km pixel and the representativeness and size of inventory plots and GLAS pixels over the landscape (29); and (iii) *prediction errors* associated with spatial analysis and mapping of AGB from significant

contributions from satellite imagery (Fig. S3) (14, 30). We combined these three types of errors (*SI Materials and Methods*) to quantify the uncertainty of total biomass carbon stock as the 95% bootstrapped confidence interval at the 1-km pixel level (Fig. 3B). The overall uncertainty in mapping AGB at the pixel scale averaged over all continental regions is estimated at $\pm 30\%$, but it is not uniform across regions or AGB ranges ($\pm 6\%$ to $\pm 53\%$) and depends on regional variations of forests, quality of remote sensing imagery, and sampling size and distribution of available ground and GLAS data. However, when averaged over all AGB ranges, regional uncertainties were comparable: $\pm 27\%$ over Latin America, $\pm 32\%$ over Africa, and $\pm 33\%$ over Asia (Fig. S4). The uncertainty in total carbon stock at the pixel scale averaged $\pm 38\%$ over all three continents after errors associated with BGB estimation were included in the analysis.

We computed the uncertainty around carbon estimates at national and regional scales by propagating errors associated with observation, including the errors associated with BGB estimates, sampling, and prediction. The uncertainty of carbon stock estimates at the national level was calculated as the square root of the sum of per-pixel errors for all pixels within the national boundary. This process reduced the relative errors as sample area increased. The national estimates were found to be constrained to within $\pm 1\%$ of the total carbon stock obtained

Canopy cover threshold

Country	10%			25%			30%		
	Area (Mha)	Total C (Gt C)	C density (Mg C/ha)	Area (Mha)	Total C (Gt C)	C density (Mg C/ha)	Area (Mha)	Total C (Gt C)	C density (Mg C/ha)
Democratic Republic of Congo	205	24	118	177	23	128	164	22	134
Cameroon	36	5	129	30	4	142	27	4	151
Republic of Congo	28	4	144	24	4	160	23	4	162
Gabon	24	4	160	22	4	164	21	4	165
Angola*	73	3	44	42	3	66	34	2	70
Total sub-Saharan Africa	775	62	80	539	50	93	447	48	106
Brazil	596	61	102	481	56	116	442	54	123
Peru	80	12	153	75	12	158	73	12	160
Colombia	84	10	122	67	9	138	64	9	141
Venezuela	61	7	118	50	7	134	47	7	139
Bolivia	74	6	84	65	6	90	61	6	94
Total Latin America	1,209	120	99	977	110	112	893	107	119
Indonesia	165	23	142	127	20	155	121	19	158
Myanmar	49	7	146	42	6	155	40	6	157
Papua New Guinea	43	6	147	37	6	152	36	6	153
India [†]	63	6	89	43	4	104	36	4	112
Malaysia	30	5	172	25	5	179	25	4	180
Total Asia and Oceania	474	65	137	359	56	155	336	54	159
Total study region	2,458	246	100	1,875	215	115	1,677	208	124

All carbon values were calculated by using the pixel-based AGB value to compute BGB and total carbon (AGB + BGB). Carbon density (Mg C ha^{-1}) values were calculated from the ratio of total carbon to total forest area at national or regional levels.

*Central African Republic replaces Angola as no. 5 in Africa using 25% and 30% canopy cover thresholds.

[†]India switches from rank 4 to rank 5 using 25% and 30% canopy cover thresholds.

from averaging the pixel mean carbon values (Table S2). Spatial aggregation using different size windows shows that the error stays bounded to within $\pm 5\%$, even at 10,000 ha (100 1-km pixels), due to the increased sample area. These errors do not include any systematic bias that may exist in biomass carbon allometry for AGB and BGB, in the in situ data inputs into the allometric equations (e.g., accurate botanical identifications for assigning wood density information, the wood density data itself, measurements of structure, etc.) or in the spatial sampling of forest biomass (SI Materials and Methods).

Discussion

The benchmark map provides a spatially refined and methodologically comparable carbon stock estimate for forests across 75 developing countries and improves upon previous assessments based on often old and incomplete national forest inventory data (27) and earlier spatial products (Fig. S5) (8, 14). Systematic quantification of the errors improves and constrains the pan-tropical estimate of total tropical forest biomass carbon (247 Gt C at 10% tree cover) and similarly national-scale carbon stocks (Table S3). Given the large uncertainty of forest carbon estimates for individual 1-km pixels (>30%), the map should be used primarily for national- and project-scale assessments (>10,000 ha). Reducing the uncertainty at the pixel level would require (i) higher-resolution data from future spaceborne radar and Lidar measurements to capture the spatial variability of forest structure and improve the estimation of aboveground biomass at spatial scales of <1 ha (21, 22) and (ii) in situ data with appropriate sampling schemes to match the scale of the remotely sensed measurements. Existing airborne Lidar and radar data can provide high-resolution estimates of project-scale forest carbon stocks (19, 21), but are likely to be unsuitable for large-scale wall-to-wall national- or continental-scale forest carbon monitoring systems.

Indeed, one key issue with any attempt to quantify forest carbon stocks is assessing the uncertainties inherent in estimating AGB from ground plots (29). Throughout this paper data associated with ground-based inventory plots have been assumed to

be error-free. Although the methods used here do represent best estimates, estimating biomass from stem diameter, using continental or pan-tropical allometric equations, will introduce non-random errors, which may be significant and systematic (6, 29). Given the paucity of information on plot-based errors, we have

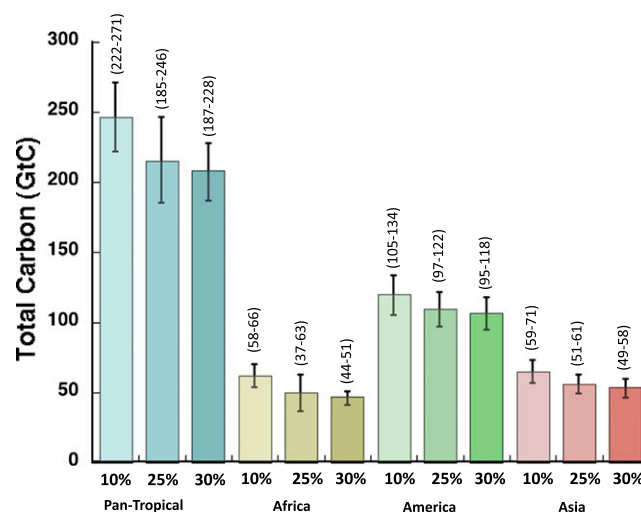


Fig. 4. Total carbon stock across the study region at three thresholds of canopy cover. Distribution of total (above- and belowground) biomass carbon stocks is shown. Carbon was computed by using the pixel-based AGB values to estimate root biomass and summing values across thresholds of percentage of tree cover (10%, 25%, and 30%) obtained from intersecting the 2001 MODIS vegetation continuous field (VCF) product ([SI Materials and Methods](#)) with the benchmark map. Similar distributions for each continent were produced separately. The error bars are based on the difference between the upper and lower limits of predicted AGB for computing total carbon ([Table S2](#)).

separated these from the other uncertainties considered in this study. By assuming that the systematic bias in estimating the carbon stock is approximately confined by the range of uncertainty of carbon predicted at the pixel level, we used the uncertainty bounds for each pixel to arrive at a range of estimates for total carbon (Fig. 4 and Table S3). However, these nonrandom errors associated with ground-based estimation of forest biomass will remain uncertain until consistent allometric equations within forest types or regions are developed.

All countries participating in a future policy mechanism to reduce emissions from deforestation and forest degradation will need to develop national- to regional-scale estimates of historic emissions (~2000–2010), which will be the starting point for generating reference emission levels. Most developing countries currently have limited data on carbon stocks of forests with which to estimate historic carbon emissions from past deforestation and degradation. Instead, countries often rely on estimates based on old or incomplete national forest inventories as reported by the Food and Agriculture Organization (31) or on Tier 1 biome-level estimates reported by the Intergovernmental Panel on Climate Change (32), neither of which are spatial in nature and thus do not allow for matching the carbon stock data with the areas undergoing change. The benchmark map presented here can assist country efforts by providing relatively fine-scale, spatially explicit and consistent forest carbon estimates that can be used with readily available remote sensing imagery to produce more robust estimates of historic emissions.

The benchmark map can also be used to assist countries in assessing the carbon emissions that are likely to be avoided by implementing different policies and programs aimed at reducing deforestation and forest degradation at regional and project scales. The map will assist developing country governments, land managers, policy makers, and civil society to become more informed about the likely result of their policies and programs in reducing national greenhouse gas emissions from the land-use sector.

Materials and Methods

Our methodological approach to mapping forest carbon stocks consists of four steps: (i) processing of ground and GLAS Lidar observations to sample forest structure and biomass over tropical regions, (ii) developing relations between

Lidar-derived Lorey's height and AGB and between AGB and BGB, (iii) mapping AGB at 1-km spatial resolution using satellite imagery to stratify tropical forest types and structure and the Maximum Entropy (MaxEnt) approach to spatially model AGB, and (iv) assessing the uncertainty in modeling the spatial distribution of AGB by validating the results and propagating the errors through the methodology to estimate the total carbon stock and its uncertainty at the national scale.

Ground data used to train the biomass prediction model were derived from various sources including published literature and national forest inventories collected by the authors and their colleagues. The plots covered a variety of forest types on each continent, including old growth moist and wet tropical forest, woodland savanna, dry forest, peat swamp forest, and forests recovering from past disturbance or clearing. To compensate for the lack of systematic spatial sampling of aboveground biomass from ground measurements, we included >3 million AGB values calculated from Lidar measurements of forest vertical structure. We used 493 calibration plots distributed over forests across three continents to convert Lorey's height inferred from Lidar measurements to AGB and used tree allometry to estimate BGB from AGB. We estimated the total biomass per plot as the sum of AGB and BGB estimates and converted the results to carbon content by using a conversion factor of 0.5. To scale our plot- and Lidar-based AGB results over the landscape, we used nonparametric spatial modeling using the MaxEnt model, which included three steps: (i) compilation of the spatially gridded remote sensing data, (ii) implementation of MaxEnt and the production of the AGB map, and (iii) estimation of prediction uncertainty. We estimated the overall uncertainty in the final benchmark map by combining the errors associated with four independent terms: measurement errors, allometry errors, sampling errors, and prediction errors. Detailed information on each step is provided in *SI Materials and Methods*.

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